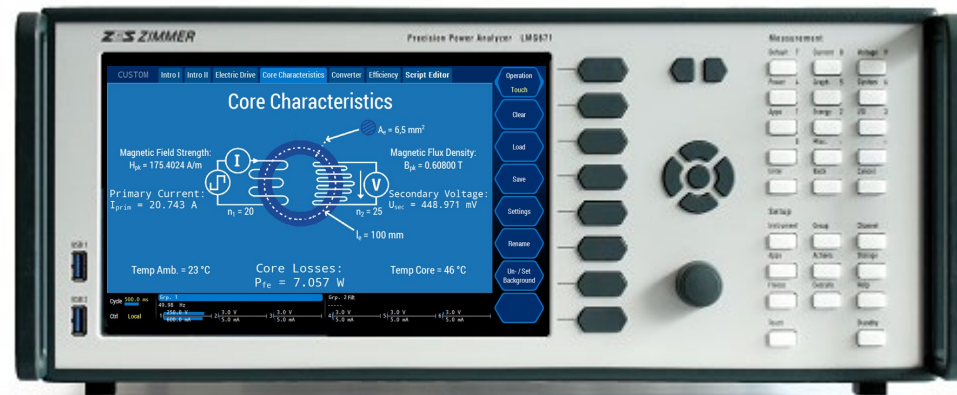


Precise Core Loss Measurement via Precision Power Analysis

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December 4, Hilton at Munich Airport



Situation today

- Power losses in magnetic components limiting factor for development of power electronics, especially core losses of different materials
- Problem gets exacerbated by new generation of wideband-gap semiconductors like SiC/GaN
- Qualification of components and materials more of an art than a science

Core losses – measure or simulate?

Challenges for simulation:

- Behavior of core materials strongly non-linear
- No generalization between soft and hard magnetic materials
- Approximative formulas resting on measured values

Advantages of measurements:

- Direct quantification of losses
- Magnetic characteristics as by-products
- Verification of theoretical models
- Basis for development of new core materials



Schematic architecture

Excitation



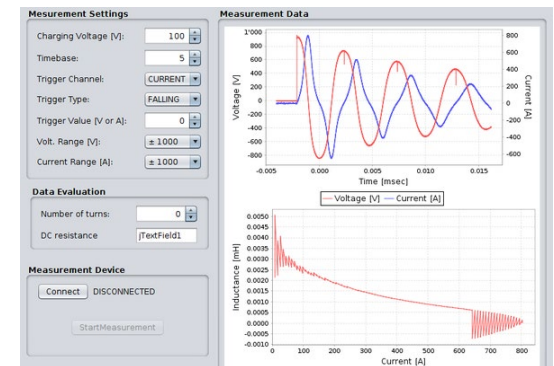
<http://www.mspm-power.de/>



Data Acquisition



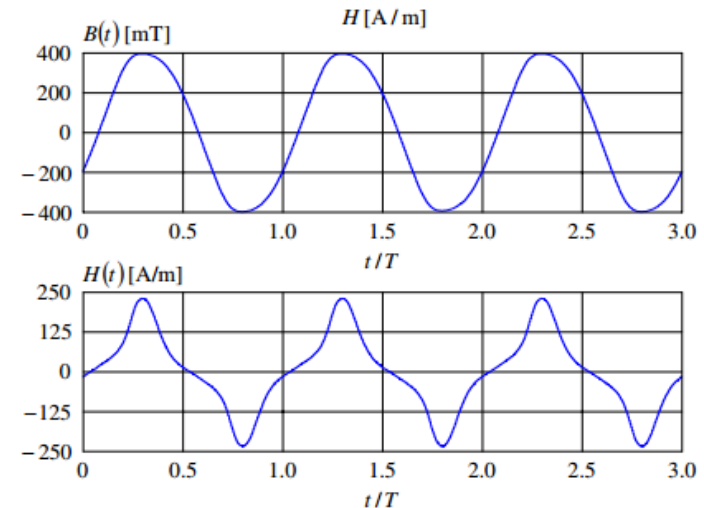
Data Processing



<https://www.powerlosstester.de/>

The common way to measure

- Standard procedures: sinusoidal field strength or flux density required
- Consequence:
 - sophisticated, expensive signal sources
 - complex measurement apparatus
- Practical relevance limited:
 - suitable signal sources allow to generate approximately sinusoidal flux density
 - field strength remains non-sinusoidal



Characteristics of field strength and flux density, [1]

Alternative approach: dumb signal, smart measurement

- Intelligent measurement apparatus allows arbitrary voltage and current waveforms
- Even mains voltage with harmonic content becomes useable
- Procedure based on measuring primary current and secondary voltage on magnetic cores – details to follow.

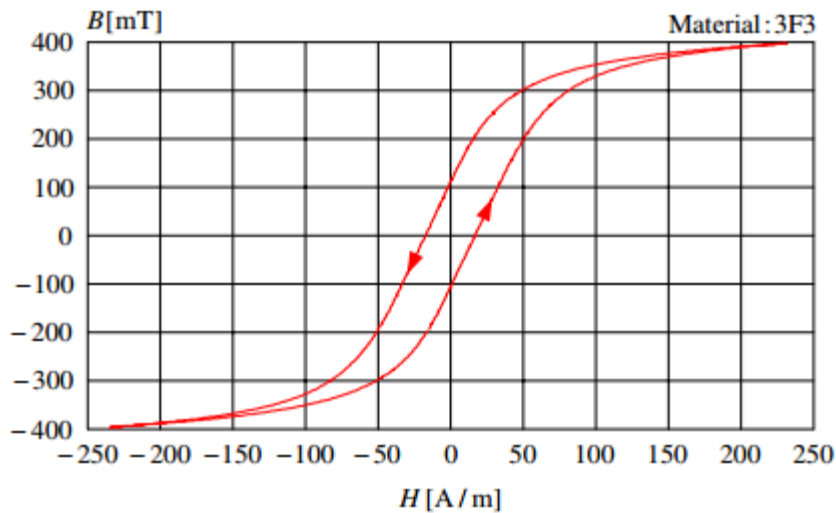


Core loss basics: components

$$\begin{aligned} P_{\text{loss}} &= P_{\text{hysteresis}} \\ &+ P_{\text{eddy_currents}} \\ &+ P_{\text{winding}} \\ &+ P_{\text{rest}} \end{aligned}$$

Core losses basics: hysteresis loop

dissipative core losses \sim area enclosed by hysteresis loop



B-H characteristics, material 3F3, [1]

$$\int H \cdot dB \sim A_H$$

$$P_H = f \cdot V_{Fe} \cdot A_H$$

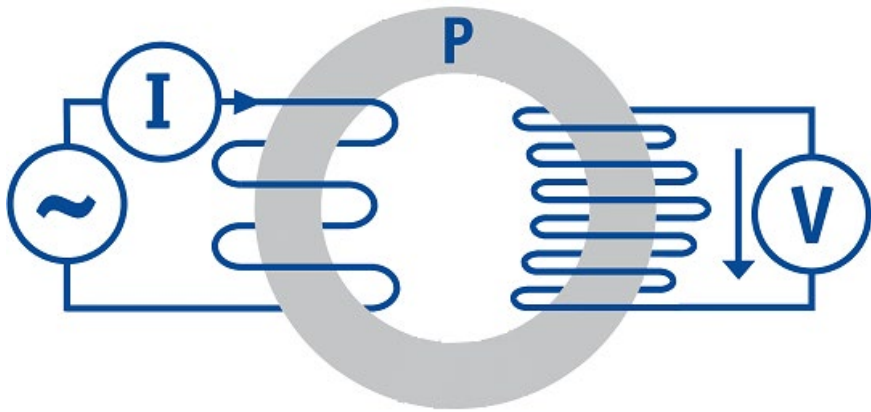
Influences on core losses:

- frequency
- temperature
- material
- geometry
- flux density

H : magnetic field strength
 A_H : area enclosed by B-H loop
 V_{Fe} : core volume

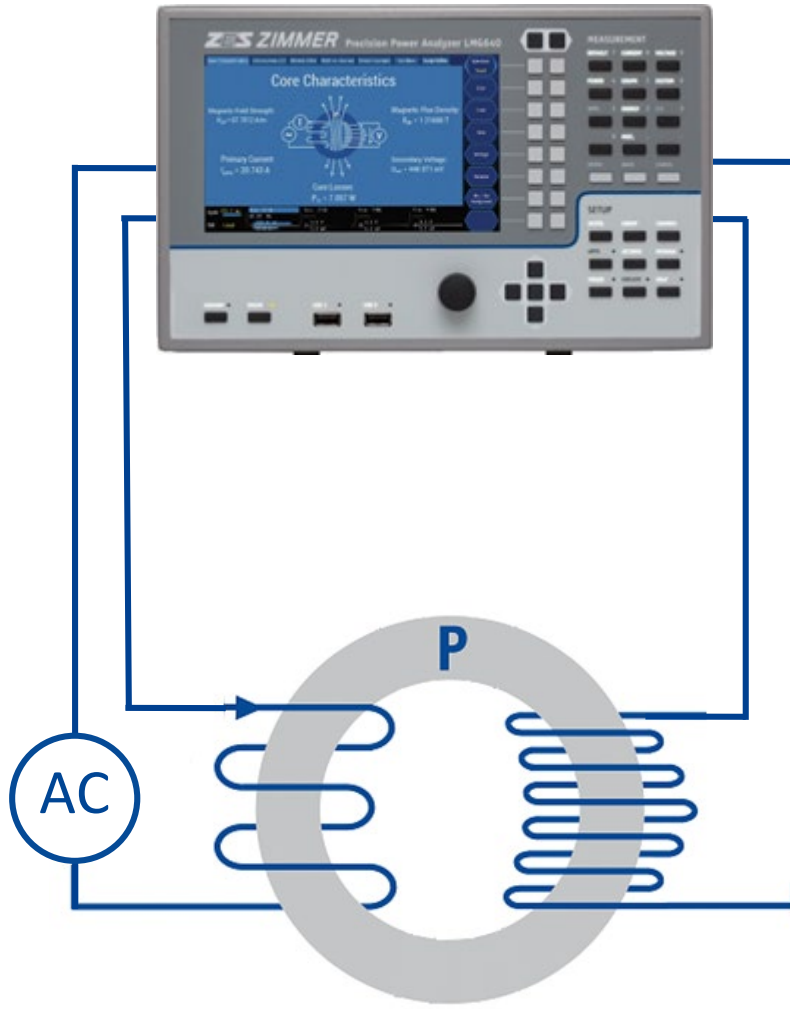
Measuring core losses: smart measurement

- ANY signal on primary side
- open circuit voltage measurement on secondary side
- $I_{\text{pk,primary}} \sim H_{\text{pk}}$
- $U_{\text{rect,secondary}} \sim B$



(P_{winding} to be excluded.)

Measuring core losses: smart measurement



$$P_{\text{loss}} = U_{\text{trms}} \cdot I_{\text{trms}} \cdot \cos\varphi \cdot \frac{n_1}{n_2}^*$$

- voltage drop on primary excluded
- no current flow on secondary

Preconditions

- optimal voltage accuracy
- optimal current accuracy
- minimal phase error

* for sinusoidal signals

Error analysis

$$\frac{\Delta P_{\text{loss}}}{P_{\text{loss}}} = \frac{\Delta U_{\text{trms}}}{U_{\text{trms}}} + \frac{\Delta I_{\text{trms}}}{I_{\text{trms}}} + \frac{\Delta \cos\varphi}{\cos\varphi}$$

The diagram illustrates the error analysis equation for relative power loss. The equation is $\frac{\Delta P_{\text{loss}}}{P_{\text{loss}}} = \frac{\Delta U_{\text{trms}}}{U_{\text{trms}}} + \frac{\Delta I_{\text{trms}}}{I_{\text{trms}}} + \frac{\Delta \cos\varphi}{\cos\varphi}$. The terms $\frac{\Delta U_{\text{trms}}}{U_{\text{trms}}}$ and $\frac{\Delta I_{\text{trms}}}{I_{\text{trms}}}$ are enclosed in blue dashed circles, and the term $\frac{\Delta \cos\varphi}{\cos\varphi}$ is enclosed in a red dashed circle. Three blue arrows point from the labels 'amplitude error voltage', 'amplitude error current', and 'phase error' to their respective terms in the equation.

amplitude error voltage

amplitude error current

phase error

Error influences – example: phase error

Taking a closer look at:

$$\frac{\cos(\varphi + \Delta\varphi)}{\cos \varphi}$$

$$\sim \frac{\Delta P_{\text{loss}}}{P_{\text{loss}}}$$

Assumptions:

primary current sinusoidal

$$f = 50\text{kHz}$$

$$\text{PF} = \cos\varphi = 0.06$$

$$\Rightarrow \varphi = \cos^{-1}(0.06) = 86.56^\circ$$

Exemplary additional skew:

$$\tau = 3.8\text{ns}$$

$$\begin{aligned}\Delta\varphi &= 2\pi \cdot f \cdot \tau = \\ &= 360^\circ \cdot 50\text{kHz} \cdot 3.8\text{ns} = \\ &= 0.0684^\circ\end{aligned}$$

$$\frac{\cos(\varphi + \Delta\varphi)}{\cos \varphi} = 0.98 \cong 2\%$$

Evaluation (with data-log file)

Batch Nr :									
Date & Time :		02-01-01, 00:13							
Piece Nr	Code Nr	Temp(°C)	Freq(kHz)	Vpp_Sp(V)	Vpp_Mv	Vrms_Mv	V_CF	V_DC	
1	0000 000 00001	25	25	11,517	11,511	4,004	1,438	-0,584	
1	0000 000 00001	25	25	23,034	23,414	8,076	1,450	-0,509	
1	0000 000 00001	25	25	34,551	34,992	12,007	1,457	-0,360	
1	0000 000 00001	25	25	46,068	46,922	15,859	1,479	-0,315	
1	0000 000 00001	25	25	57,585	58,176	19,380	1,501	-0,281	
1	0000 000 00001	25	25	69,102	70,065	22,433	1,562	-0,156	



Ipp_Mv(A)	Irms_Mv	I_CF	I_DC
0,212	0,073	1,451	-0,001
0,385	0,133	1,450	0,001
0,537	0,184	1,460	0,002
0,722	0,240	1,501	0,004
0,979	0,313	1,570	-0,019
1,380	0,421	1,645	-0,013

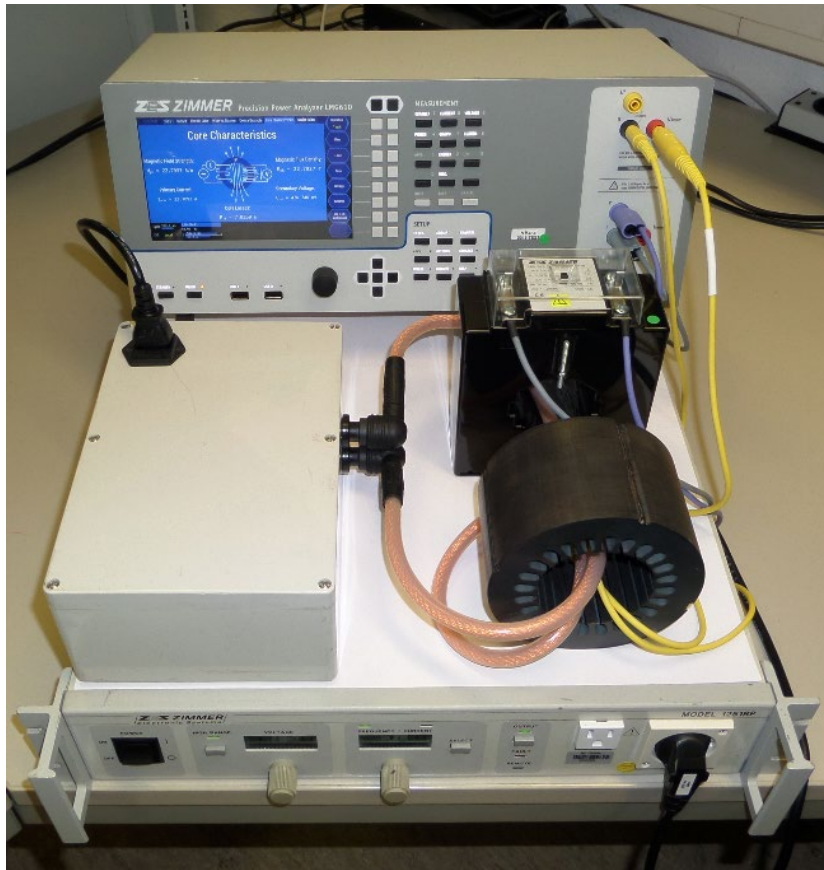


PhaseShift	Phi_Cal	Phi_Corrected	CosQ
1,457	76,503	75,062	0,258
1,457	74,435	72,978	0,293
1,457	72,654	71,196	0,322
1,457	71,622	70,177	0,339
1,457	71,965	70,558	0,333
1,457	73,774	72,456	0,301



Pv_Cal(mW)	Pv_Corrected	Pv_Final	Pv_FinalOffset
68,357	75,501	79,910	78,504
287,997	314,175	318,410	316,329
658,207	711,587	734,394	729,695
1201,240	1292,009	1366,165	1358,309
1879,682	2020,949	2263,251	2243,208
2636,412	2844,095	3488,736	3465,131

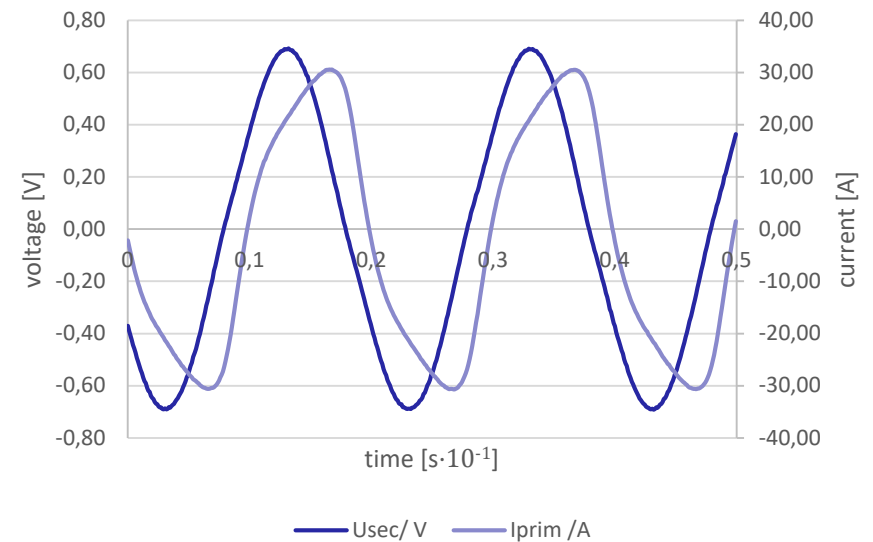
Example setup: laminated core / electric motor



ZES ZIMMER LMG610

AC source: 115V
frequency: 50Hz

$$\frac{n_1}{n_2} = \frac{2}{2} = 1$$



Calculating peak value of magnetic field strength

According to the Maxwell–Ampère equation:

$$\oint \vec{H} d\vec{s} = \int_A \vec{J} d\vec{A} + \frac{d}{dt} \int_A \vec{D} d\vec{A}$$

Assuming quasi-stationary fields: $\omega\varepsilon \ll 1$

$$H_{pk} = \frac{I_{pk} \cdot n_1}{l_{magn}}$$

H_{pk} : peak value of magnetic field strength

I_{pk} : peak value of primary current

n_1 : no. of primary windings

l_{magn} : magnetic path length

Calculating peak value of magnetic field strength

Signal shape of primary current irrelevant, as long as symmetrical:

$$I_{pk} = \frac{I_{pp}}{2}$$

Resulting formula for H_{pk} :

$$H_{pk} = \frac{I_{pp}}{2} \cdot \frac{n_1}{l_{magn}}$$

- H_{pk} : peak value of magnetic field strength
- I_{pp} : peak-to-peak value of primary current
- n_1 : no. of primary windings
- l_{magn} : magnetic path length

Calculating peak value of magnetic flux density

From the Maxwell–Faraday equation :

$$\frac{1}{dA} \oint \vec{E} d\vec{s} = -\frac{d\vec{B}}{dt}$$

Assuming quasi-stationary fields: $\omega\varepsilon \ll 1$

$$-\frac{1}{n_2 \cdot A} \cdot u(t) = \frac{dB(t)}{dt}$$

- $B(t)$: magnetic flux density
- $u(t)$: induced secondary voltage
- n_2 : no. of secondary windings
- A : core cross section

Calculating peak value of magnetic flux density

Integrating the induced voltage between two zero crossings allows us to calculate the peak value of magnetic flux density:

$$-\frac{1}{n_2 \cdot A} \cdot \int_{t_0}^{t_1} u(t) dt = B_{pp}$$

- B_{pp} : peak-to-peak value of magnetic flux density
- $u(t)$: induced secondary voltage
- n_2 : no. of secondary windings
- A : core cross section

Calculating peak value of magnetic flux density

Since the induced voltage has no DC content:

$$\int_{t_0}^{t_1} u(t) dt = - \int_{t_1}^T u(t) dt = \frac{1}{2} \int_{t_0}^T |u(t)| dt$$

From the definition of the rectified value we know:

$$U_{rect} = \frac{1}{T} \int_0^T |u(t)| dt$$

Calculating peak value of magnetic flux density

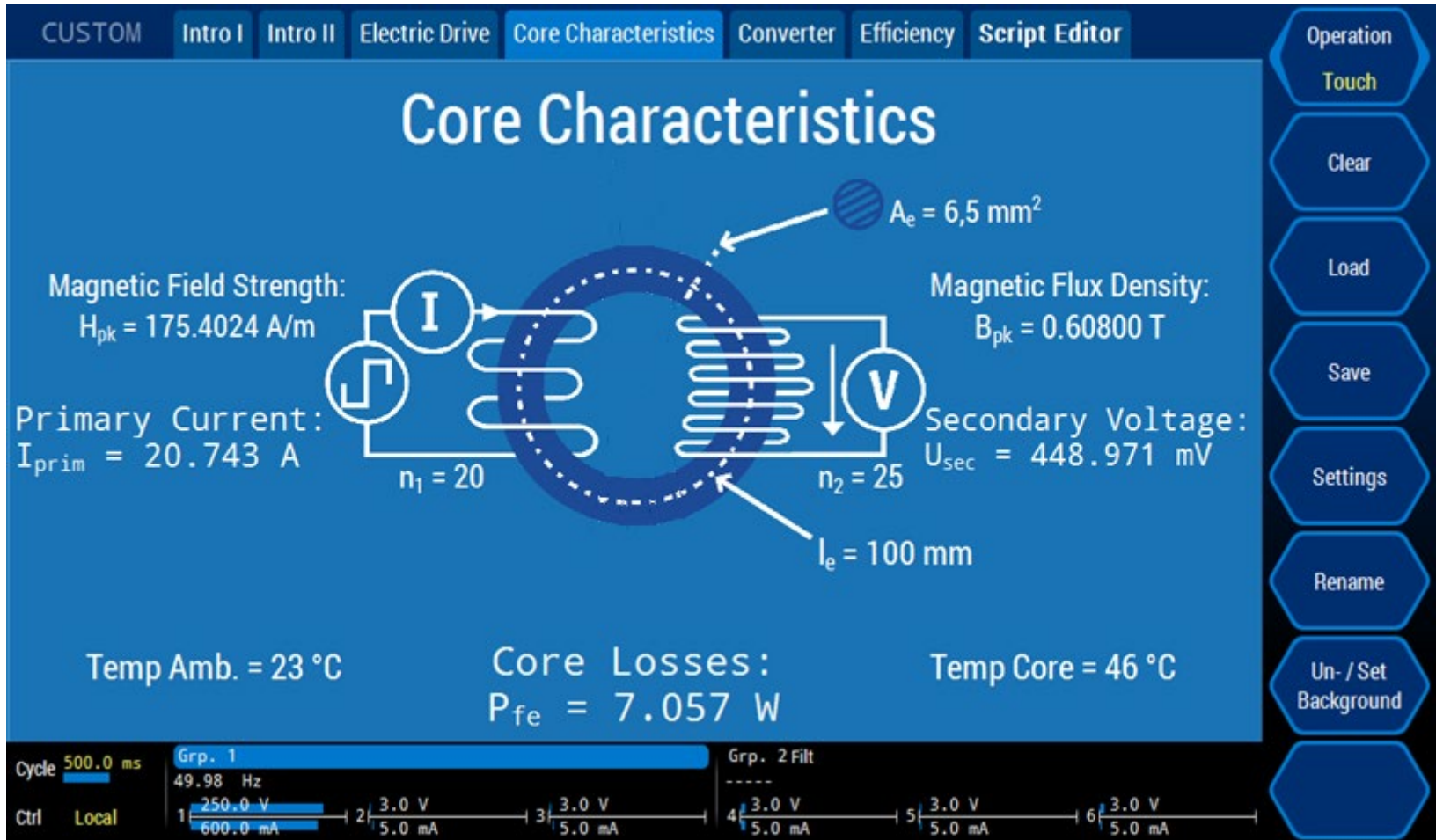
Thus, the peak value of flux density can be expressed as:

$$B_{pk} = \frac{U_{rect}}{4 \cdot f \cdot n_2 \cdot A}$$

The calculation is independent of signal shape. Taking into account the windings ratio, core losses can be established as:

$$P_{loss} = P \cdot \frac{n_1}{n_2}$$

Comprehensive results



Outlook: further possibilities

In analogy to:

$$-\frac{1}{n_2 \cdot A} \cdot \int_{t_0}^{t_1} u(t) dt = B_{pp}$$

the following parameters can also be derived:

energy	E	$\int_{t_0}^{t_1} (u \cdot i) dt$
charge	Q	$\int_{t_0}^{t_1} (i) dt$
magnetic flux	Φ	$\int_{t_0}^{t_1} (u) dt$
Joule heating integral	I^2t	$\int_{t_0}^{t_1} (i^2) dt$

Take-home messages

- By directly measuring frequency, the peak value of primary current and the rectified value of secondary voltage, core losses can be calculated with high accuracy.
- The basis of precise core loss measurement is the precise measurement of voltage, current and power.
- Depending on the frequency range used, both ample analog bandwidth and minimal phase error, also at high frequencies, are mandatory.
- Every detail of the measurement setup matters when it comes to minimizing overall error.
- For a known core geometry, the peak value of magnetic field strength and flux density as well as relative permeability can be derived in the same measurement without additional effort.

Questions?

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Thank you very much for your attention!

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